

ECE 2300 Digital Logic and Computer Organization Fall 2024

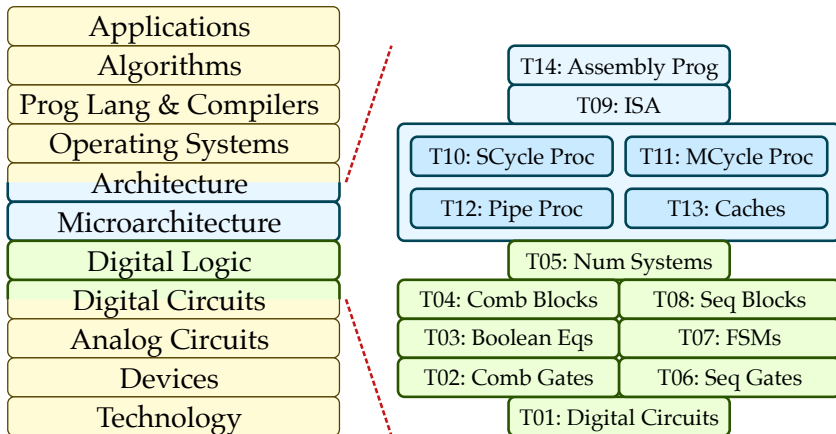
Topic 8: Sequential Building Blocks

School of Electrical and Computer Engineering
Cornell University

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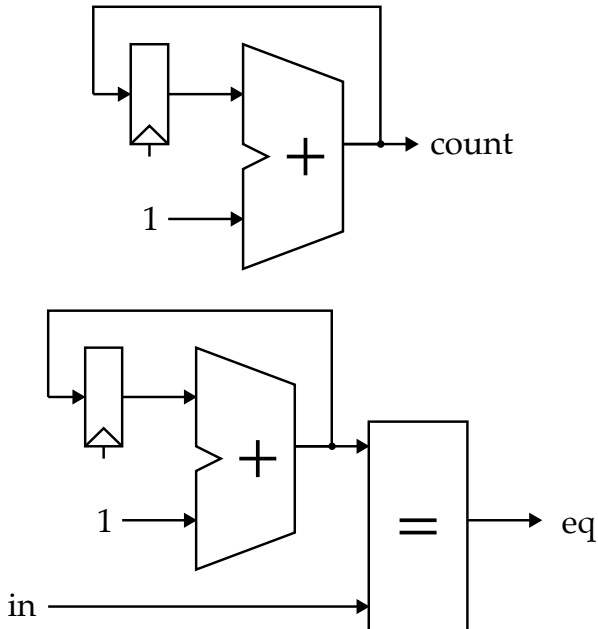
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1. Counters

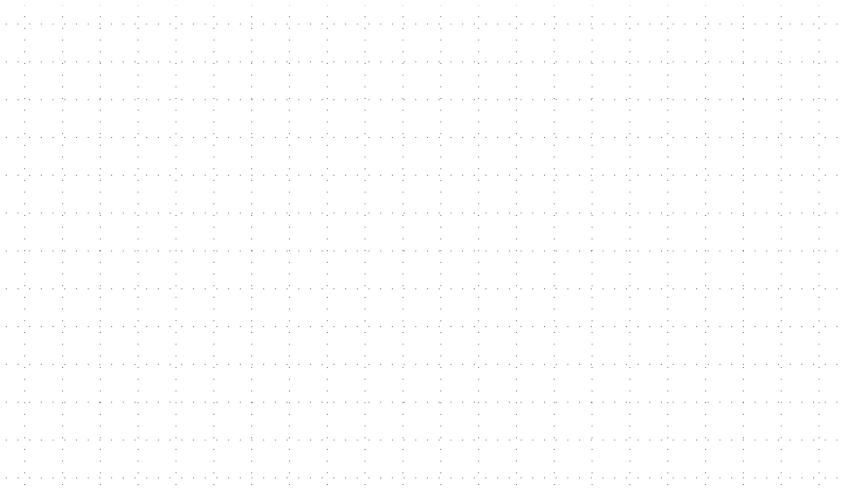


Summary of Kinds of Counters

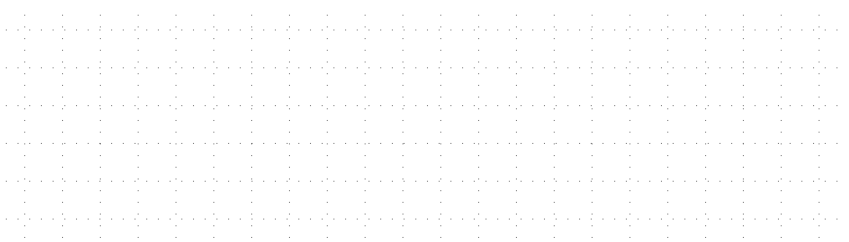
- Counters with enable and/or clear
- Up, down, up/down counters
- Variable increment counters (count by more than one)
- Variable start counters (control starting value)
- Decade counters (counts to ten then wraps around)
- Saturating counters (does not wrap around)

Implement an increment-by-one clearable up/down counter.

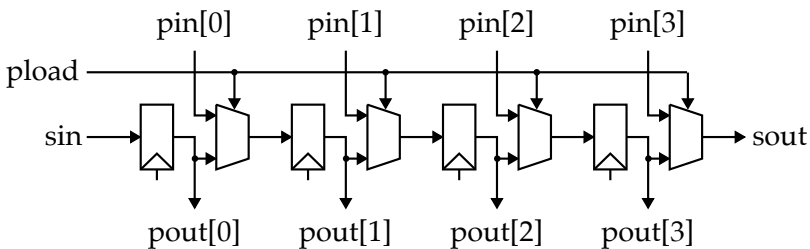
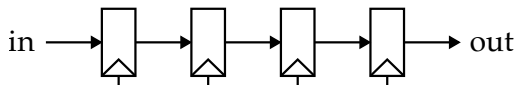
- clear: if 1 then clear counter, counter outputs zero following cycle
- updown: if 1 then count up by one, if 0 then count down by 1
- done: should be 1 if counter is at zero on current cycle
- counter should roll-over



Derive setup time constraint (max-delay constraint) as a function of the flip-flop timing parameters and the combinational block delays.



2. Shift Registers



Summary of Kinds of Shift Registers

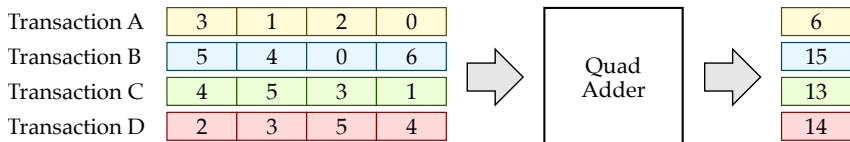
- Serial-in, serial-out shift registers
- Parallel-in, serial-out shift registers
- Serial-out, parallel-out shift registers
- Bi-directional shifters (can shift left and shift right)
- Variable shift registers (can vary shift amount)

Derive hold time constraint (min-delay constraint) as a function of the flip-flop timing parameters and the combinational block delays for the serial-in/out, parallel-in/out shift register.



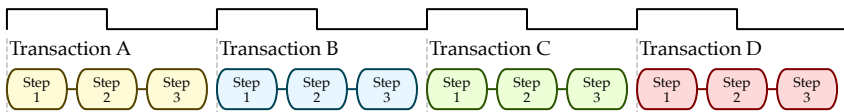
3. Sequential Arithmetic

- A quad adder adds four 4-bit input values to produce one 4-bit output value (ignore overflow)

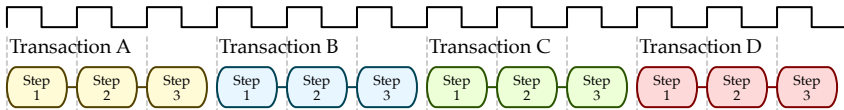


- A *transaction* involves processing a block of four 4-bit values
- The quad adder executes a *sequence* of transactions
- Each *transaction* can be broken down into three steps
 - Step 1. Add element 0 and element 1
 - Step 2. Add element 2 to the result of step 1
 - Step 3. Add element 3 to the result of step 2

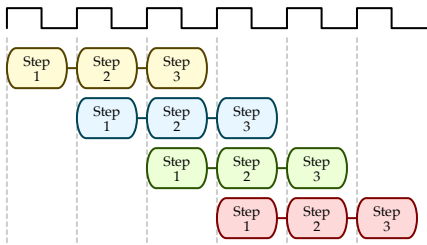
Single-Cycle Quad Adder



Multi-Cycle Quad Adder



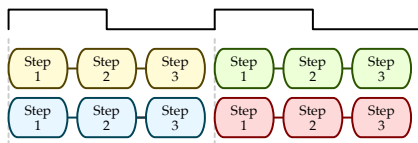
Pipelined Quad Adder



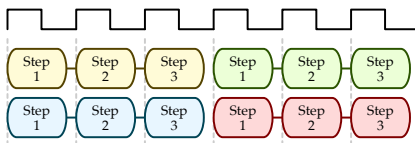
$$\frac{\text{Time}}{\text{Sequence}} = \frac{\text{Transactions}}{\text{Sequence}} \times \frac{\text{Avg Cycles}}{\text{Transaction}} \times \frac{\text{Time}}{\text{Cycle}}$$

	Area	$\frac{\text{Avg Cycles}}{\text{Trans}}$	$\frac{\text{Time}}{\text{Cycle}}$
Single-Cycle	medium	1	long
Multi-Cycle	small	3	short
Pipelined	large	≈ 1	short

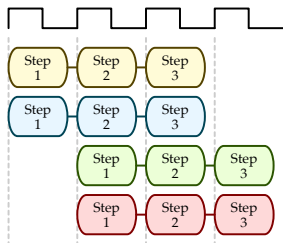
Parallel Single-Cycle Quad Adder



Parallel Multi-Cycle Quad Adder



Parallel Pipelined Quad Adder



$$\frac{\text{Time}}{\text{Sequence}} = \frac{\text{Transactions}}{\text{Sequence}} \times \frac{\text{Avg Cycles}}{\text{Transaction}} \times \frac{\text{Time}}{\text{Cycle}}$$

	Area	$\frac{\text{Avg Cycles}}{\text{Trans}}$	$\frac{\text{Time}}{\text{Cycle}}$
Parallel Single-Cycle	$2 \times \text{Single-Cycle}$	0.5	long
Parallel Multi-Cycle	$2 \times \text{Multi-Cycle}$	1.5	short
Parallel Pipelined	$2 \times \text{Pipelined}$	≈ 0.5	short

- Our goal is to do a quantitative comparative analysis of area and performance across six different implementations

$$\frac{\text{Time}}{\text{Sequence}} = \frac{\text{Transactions}}{\text{Sequence}} \times \frac{\text{Avg Cycles}}{\text{Transaction}} \times \frac{\text{Time}}{\text{Cycle}}$$

	Area	$\frac{\text{Trans}}{\text{Sequence}}$	$\frac{\text{Avg Cycles}}{\text{Trans}}$	$\frac{\text{Time}}{\text{Cycle}}$	$\frac{\text{Time}}{\text{Sequence}}$
Single-Cycle		100			
Multi-Cycle		100			
Pipelined		100			
Parallel SCycle		100			
Parallel MCycle		100			
Parallel Pipe		100			

Constant Delay Model

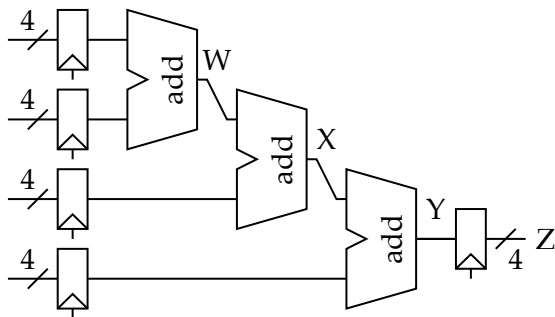
	t_{pd}
4-bit 2-to-1 Mux	8τ
4-bit 3-to-1 Mux	10τ
4-bit Adder	40τ
4-bit Reg Clk-to-Q	9τ
4-bit Reg Setup	10τ

Area Model

	Area
4-bit 2-to-1 Mux	4α
4-bit 3-to-1 Mux	8α
4-bit Adder	12α
4-bit Reg	11α

3.1. Single-Cycle Quad Adder

Area



Time/Cycle

Simulation Table

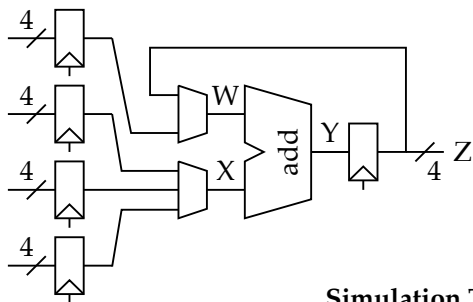
Cycle	Input	After Reg	W	X	Y	Z
0	3, 1, 2, 0					
1	5, 4, 0, 6					
2	4, 5, 3, 1					
3	2, 3, 5, 4					
4						
5						

Transaction Diagram

	0	1	2	3	4	5	6	7	8	9	10	11	12	13
Transaction A														
Transaction B														
Transaction C														
Transaction D														

3.2. Multi-Cycle Quad Adder

Area



Time/Cycle

Simulation Table

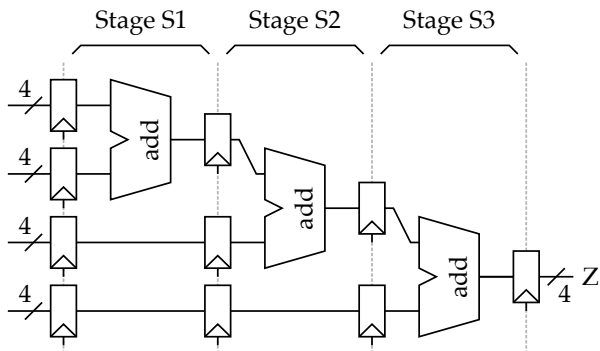
Cycle	Input	After Reg	W	X	Y	Z
0	3, 1, 2, 0					
1						
2						
3	5, 4, 0, 6					
4						
5						
6						

Transaction Diagram

	0	1	2	3	4	5	6	7	8	9	10	11	12	13
Transaction A														
Transaction B														
Transaction C														
Transaction D														

3.3. Pipelined Quad Adder

Area



Time/Cycle

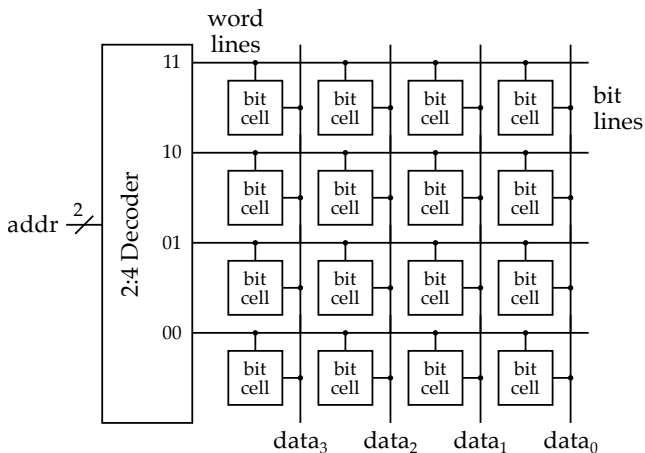
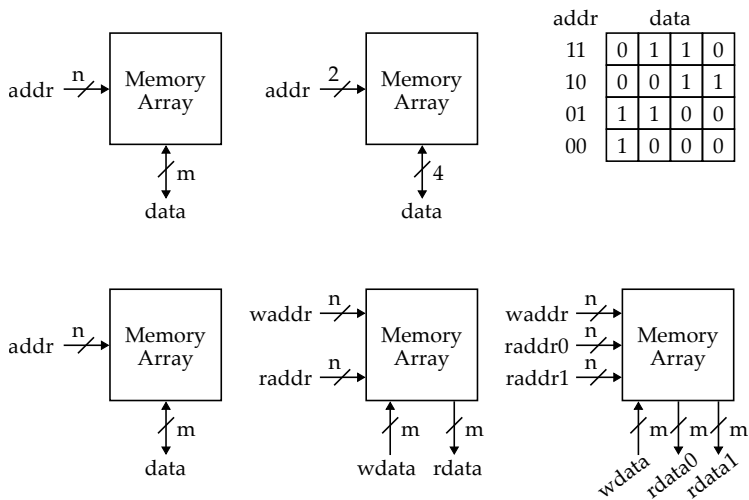
Simulation Table

Cycle	Input	Stage S1	Stage S2	Stage S3	Z
0	3, 1, 2, 0				
1	5, 4, 0, 6				
2	4, 5, 3, 1				
3	2, 3, 5, 4				
4					

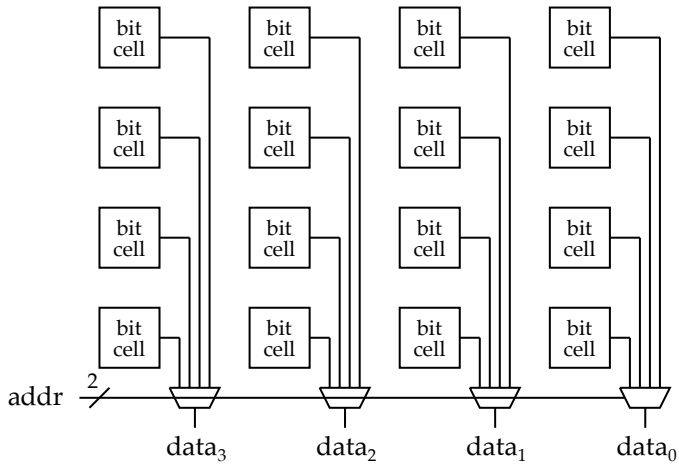
Transaction Diagram

	0	1	2	3	4	5	6	7	8	9	10	11	12	13
Transaction A														
Transaction B														
Transaction C														
Transaction D														

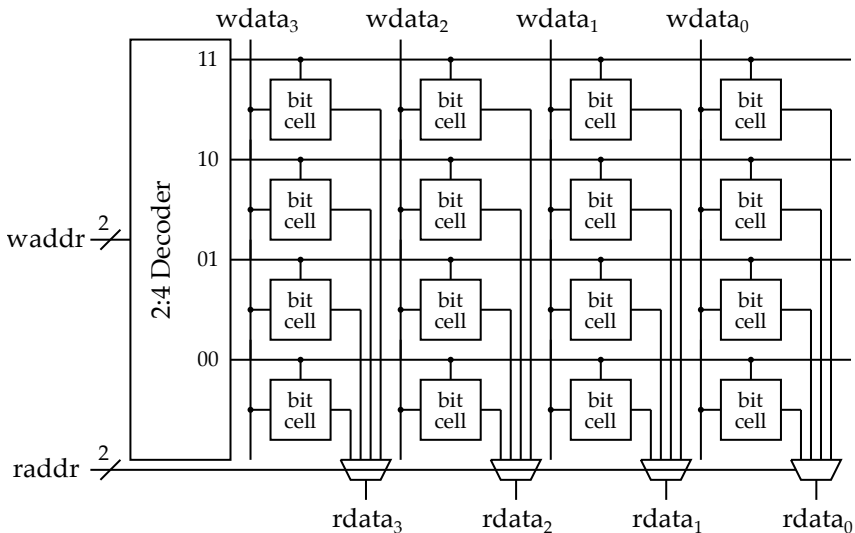
4. Memory Arrays



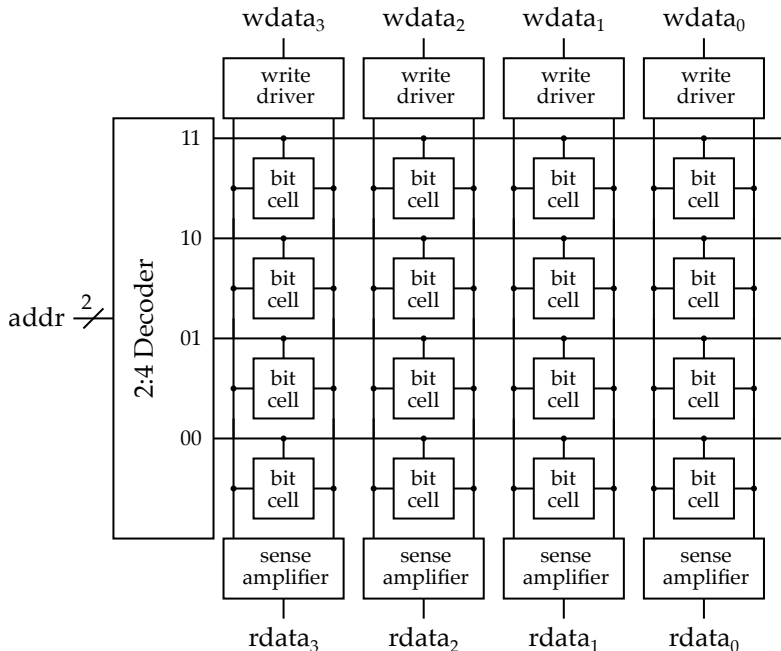
4.1. Read-Only Memories



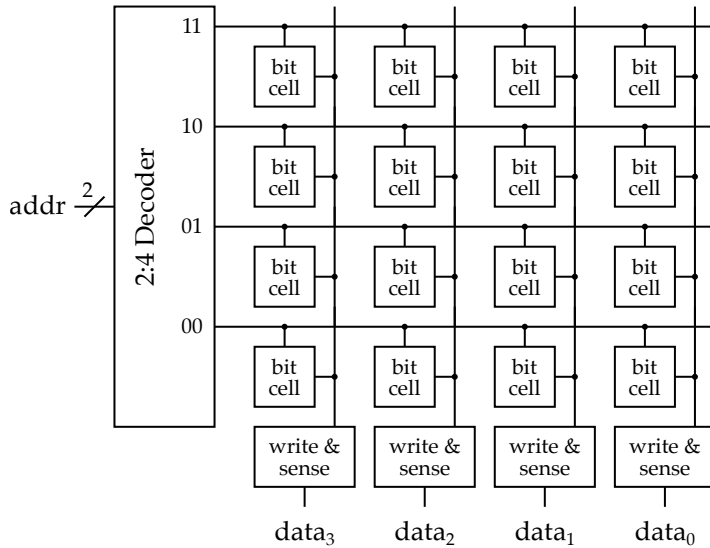
4.2. Register Files



4.3. Static Random Access Memories (SRAM)



4.4. Dynamic Random Access Memories (DRAM)



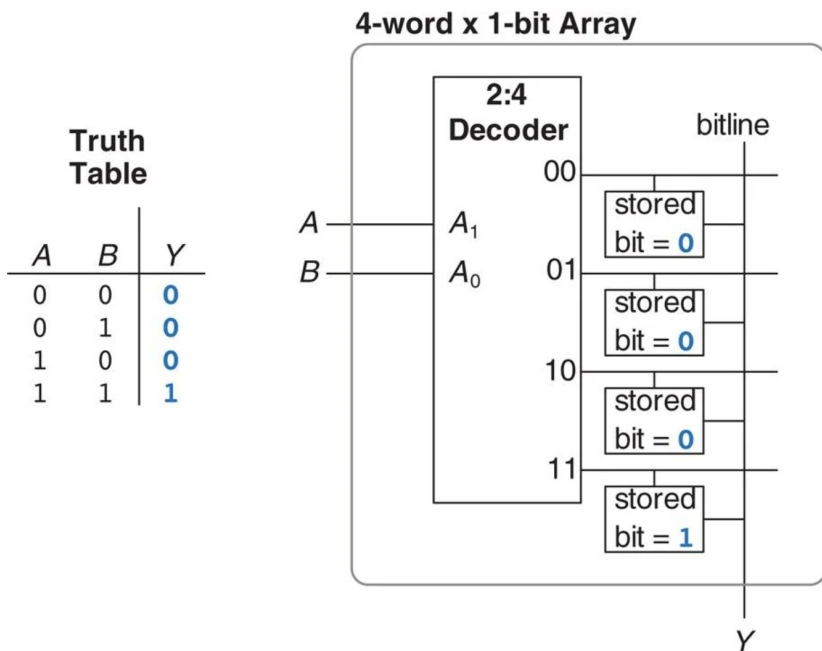
4.5. Comparing Memory Arrays

Memory Type	Transistors per Bit Cell	Density	Latency
Register File			
SRAM			
DRAM			

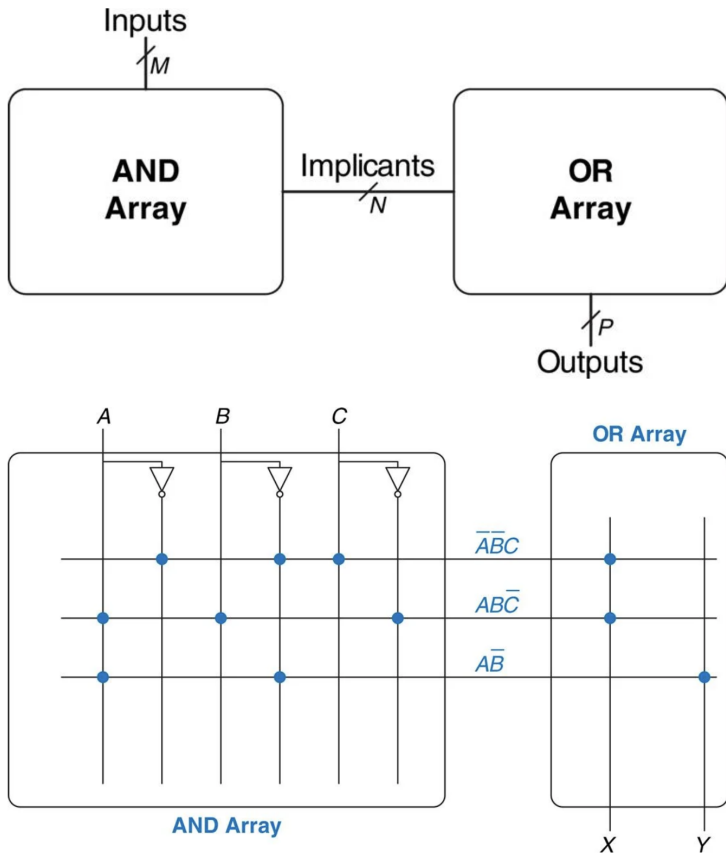
5. Programmable Logic

- Programmable logic uses sequential logic-gates to enable reconfiguring (“programming”) the behavior of hardware after a chip has been fabricated

5.1. Programmable Truth Tables



5.2. Programmable Logic Arrays



5.3. Field Programmable Gate Arrays

